# ON THE ACCURACY OF CONSERVATION OF THE ADIABATIC INVARIANT* 

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A Hamiltonian system with one degree of freedom is considered. The system depends on the parameter $\xi$ which varies slowly with time $t: \xi=\xi(\varepsilon t), 0<\varepsilon \ll 1$ and tends in a sufficiently regular manner to well defined limits as $t \rightarrow \pm \infty$. When $t \rightarrow \pm \infty$, the adjabatic invariant, acting along the trajectory of such system, has the limit meanings $I_{ \pm}$. Their difference $\Delta I=I_{+}-I_{-} \quad$ is estimated。
The problem of estimating $\Delta I$ appears in classical mechanics / $1,2 /$, quantum mechanics /3/ and in the theory of waveguides /4/. In the case when the dependence of $\xi$ on $\varepsilon t$ is finite $(\xi(\varepsilon t)=$ const for sufficiently large $\varepsilon t)$ and infinitely differentiable, the author of $/ 5 /$ shows that $\Delta I$ decreases, as $\varepsilon \rightarrow 0$, faster than any power of $\varepsilon$. For the linear systems with the frequency depending analytically on $\varepsilon t$, the known asymptotic of $\Delta I$ is found to be exponential $\Delta I=O(\exp (-c / \varepsilon)), c=$ const $/ 3,6 /$. An erroneous proof of the exponential smallness of $\Delta I$ in given in $/ 1 /$ for the case of an analytic $\xi(\varepsilon t)$ for the general nonlinear systems.

Below the problem of estimating $\Delta I$ is considered with help of the perturbations procedure in the action-angle variables. For the case when the dependence of $\xi$ on $\varepsilon t$ is finite and has a finite smoothness, a power asymptotics is obtained for $\Delta I$ and the exponential smallness of $\Delta I$ in $\varepsilon$ is proved for the case of analytic $\xi(e t)$.

1. Equations in the action-angle variables. The Hamiltonian of the problem in question has the form

$$
\begin{equation*}
E=E(p, q, \xi), \quad \xi=\xi(\lambda), \quad \lambda=\varepsilon t \tag{1.1}
\end{equation*}
$$

where $p$ and $q$ denote the canonical variables. We assume that $E$ is an analytic function of $p, q$ and $\xi$.

Let a region filled with closed trajectories exist for every $\xi$ on the phase plane of the unperturbed ( $\xi=$ const) problem. The action-angle variables of the unperturbed problem are defined in this region $/ 1 /$. The action $I=I(p, q, \xi)$ is an area divided by $2 \pi$, bounded by an unperturbed trajectory passing through the point $(p, q)$. The angle $\varphi=\varphi(p, q, \xi) \bmod 2 \pi$ is an angular coordinate along the trajectory, varying uniformly in the unperturbed system. The variable change $p, q \rightarrow I, \varphi$ is canonical and time-dependent. The change of the variables $I, \varphi$ in the initial problem is described by a Hamiltonian system with the Hamiltonian

$$
\begin{equation*}
H(I, \varphi, \lambda)=H_{0}(I, \lambda)+\varepsilon H_{\mathrm{1}}(I, \varphi, \lambda) \tag{1.2}
\end{equation*}
$$

where $H_{0}$ is the original Hamiltonian of $E$ expressed in terms of $I$ and $\lambda$

$$
\begin{align*}
& H_{1}=(d \xi / d \lambda) G(I, \varphi, \lambda)  \tag{1.3}\\
& G=\frac{1}{\omega}\left[-\int_{0}^{\varphi} \frac{\partial E}{\partial \xi} d \varphi+\frac{\varphi}{2 \pi} \int_{0}^{2 \pi} \frac{\partial E}{\partial \xi} d \varphi\right] \\
& \omega=\omega(I, \lambda)=\partial H_{0} / d I
\end{align*}
$$

and $H$ is an analytic function of $I$ and $\varphi$, and $2 \pi$-periodic in $\varphi$.
We shall use the angle brackets $\langle\cdot\rangle \varphi$ for the $2 \pi$-periodic functions of $\varphi$ to denote the averaging over $\varphi$, and the curly brackets $\{\cdot\}^{\varphi}$ for the purely periodic part: $\{\cdot\}^{\varphi}=(\cdot)-\langle\cdot\rangle^{\varphi}$. Further, in order to reduce the amount of notations used we shall assume that $\left\langle H_{1}\right\rangle^{\varphi}=0$, otherwise we shall have to replace, in the arguments that follow, $H_{0}$ by $H_{0}+\varepsilon\left\langle H_{1}\right\rangle^{\varphi}$, and $H_{1}$ by $\left\{H_{1}\right\}^{\varphi}$.
2. The procedure of the perturbation theory. The procedure described here of asymptotic integration of the system with the Hamiltonian (1.2), analogous to that given in /7/, will be used to obtain the estimates of variation in the value of the adiabatic invariant.

Let us carry out, in the system with the Hamiltonian (1.2), a canonical, nearly identical variable transformation with a so far undefined generating function $W=J \varphi+\varepsilon S(J, \varphi, \lambda)$. Here $J$ and $\psi$ are the new canonical variables connected with $I$ and $\varphi$ by the relations

[^0]\[

$$
\begin{equation*}
I=J+\varepsilon \frac{\partial S}{\partial \varphi}, \quad \varphi=\varphi+\varepsilon \frac{\partial S}{\partial J} \tag{2.1}
\end{equation*}
$$

\]

The variation in $J$ and $\psi$ is described by a Hamiltonian system with the Hamiltonian

$$
\begin{equation*}
\Phi(J, \psi, \lambda)=\varepsilon^{2} \frac{\partial S}{\partial \lambda}+H_{0}\left(J+\varepsilon \frac{\partial S}{\partial \varphi}\right)+\varepsilon H_{1}\left(J+\varepsilon \frac{\partial S}{\partial \varphi}, \varphi, \lambda\right) \tag{2.2}
\end{equation*}
$$

In the right-hand part of (2.2) $\varphi$ must be expressed in terms of $J$ and $\psi$ in accordance with (2.1). Let us choose

$$
S=\frac{1}{\partial H_{0} / \partial T}\left\{\int_{0}^{\varphi} H_{1} d \varphi\right\}^{\varphi}
$$

Since $\left\langle H_{1}\right\rangle^{\varphi}=0$, the above expression is correct and $S$ is a $2 \pi$-periodic function of $\varphi$ with a zero mean value. For $S$ chosen in such a manner we have

$$
\begin{align*}
& \Phi=H_{0}(J, \lambda)+\varepsilon^{2} F  \tag{2.3}\\
& \varepsilon^{2} F=\varepsilon^{2} \frac{\partial S}{\partial \lambda}+\left(H_{0}\left(J+\varepsilon \frac{\partial S}{\partial \varphi}, \lambda\right)-H_{0}(J, \lambda)-\varepsilon \frac{\partial H_{0}(J, \hat{\lambda})}{\partial J} \frac{\partial S}{\partial \Phi}\right)+ \\
& \varepsilon\left(H_{1}\left(J+\varepsilon \frac{\partial S}{\partial \Phi}, \varphi, \lambda\right)-H_{1}(J, \varphi, \lambda)\right), \quad F=O(1)
\end{align*}
$$

Let us denote

$$
\Phi_{0}=H_{0}+\varepsilon^{2}\langle F\rangle^{\oplus}, \quad \Phi_{1}=(F)^{\Phi}
$$

Then the Hamiltonian will become

$$
\Phi=\Phi_{0}(J, \lambda)+\varepsilon^{2} \Phi_{1}(J, \psi, \lambda)
$$

which is completely analogous to (1.2) except that the term depending on the phase $\psi$ is now of the order of $\varepsilon^{2}$. Repeating the above procedure once more, we obtain a Hamiltonian in which the phase dependence appears only in the terms of the order of $\varepsilon^{3}$. Finally, aftex
$n$ steps of the above procedure we obtain the Hamiltonian in the form

$$
\begin{equation*}
\Phi(J, \varphi, \lambda)=\Phi_{0}(J, \lambda)+e^{n+1} \Phi_{1}(J, \psi, \lambda) \tag{2.4}
\end{equation*}
$$

where the new variables and the Hamiltonian are still expressed in terms of $J, \psi$ and $\Phi$. Neglecting in the Hamiltonian (2.4) the last term, we obtain the following relations for the variation of $J$ and $\psi$ with time:

$$
\begin{equation*}
J=\text { const, } \quad \psi=\psi_{0}+\frac{1}{\varepsilon} \int_{\lambda_{\mathrm{e}}}^{\lambda} \frac{\partial \Phi_{0}(J, v)}{\partial J} d v, \quad \psi_{0}=\text { const } \tag{2,5}
\end{equation*}
$$

Analysis of the corrections brought in by each consecutive step of the procedure shows that the relations (2.5) describe the variation in $J$ with the accuracy of $O\left(e^{n+1}\right)$ and in $\psi$ with the accuracy of $O\left(e^{n}\right)$ on the time intervals of the order 1 ie (provided that the step in question is feasible). From (2.3) we see that every step of the procedure reduces the smoothness of the Hamiltonian with respect to $\lambda$, by 1 . It follows therefore that the number of steps which can be carried out depends on the smoothness $H$ of the Hamiltonian with respect to $\lambda$.
3. The asymptotics of variation of the adiabatic invariant for a finite perturbation of finite smoothness. Let the perturbation be finite $\xi(\lambda) \equiv$ const for $\lambda<\lambda_{-}$and $\lambda>\lambda_{+}$, where $\lambda_{ \pm}$are constant. Let the first $n-1$ derivatives of $\xi(\lambda)$ be continuous (and hence vanish) at the point $\lambda_{ \pm}$, and the $n$-th derivative be discontinuous, i.e. $n \geqslant 1$. Let the function $\xi(\lambda)$ be differentiable $n+2$ times for $\lambda \in\left(\lambda_{-}, \lambda_{+}\right)$and its derivatives bounded. We shall calculate the asymptotics of varıation of the adiabatic invariant.

Let us denote by $I(\lambda), \varphi(\lambda)$ the solution of a system with the Hamiltonian (1.2) and $I_{ \pm}=I\left(\lambda_{+}\right), \quad \varphi_{-}=\varphi\left(\lambda_{-}\right), \Delta I=I_{+}-I_{-}$. We shall write, for a $2 \pi$-periodic function $f(\varphi)$ with zero mean value

$$
(L f)(\varphi)=-\left\{\int_{0}^{\varphi} f(\gamma) d \gamma\right\}^{\varphi}
$$

Theorem 1. The quantity $\Delta I$ has the following asymptotics

$$
\left.\Delta I=\varepsilon^{n}\left(R\left(\lambda_{+}-0\right)-R\left(\lambda_{-}+0\right)\right)+O\left(\varepsilon^{n+1}\right), \quad R(\lambda)=-\frac{\xi^{(n)}(\lambda)}{\epsilon^{n}\left(I_{-} \lambda\right)}\left(L^{n-1} G\right)\left(I_{-}, \varphi_{*}(\lambda), \lambda\right) \quad \text {, } 3.1\right)
$$

where $L^{n-1}$ denotes the operator $L$ raised to the $(n-1)$-th power, $G$ is given by (1.3), and

$$
\varphi_{*}(\lambda)=\varphi_{-}-\varepsilon^{-1} \int_{\lambda_{-}}^{\lambda} \omega\left(I_{-}+\varepsilon \frac{H_{1}\left(1, \varphi_{-} \lambda_{-}+0\right)}{\omega\left(I_{-}, \lambda_{-}\right)}, v\right) d v
$$

Proof. When $\lambda \hookleftarrow\left(\lambda_{-}, \lambda_{+}\right)$, the smoothness allows $n+1$ steps of the procedure given in Sect.2. Let us denote by $(J, \psi)$ the variables introduced in the $n-t h$ step, and by $W=$ $J \varphi+\varepsilon S(J, \varphi, \lambda)$ the generating function of the substitution $(I, \varphi) \rightarrow(J, \psi)$ Let $J(\lambda), \psi(\lambda)$ denote the solution $I(\lambda), \varphi(\lambda)$ in terms of the variables $(J, \psi)$. From the formulas for the substitution of variables it follows that

$$
\begin{equation*}
I\left(\lambda_{+}\right)-I\left(\lambda_{-}\right)=J\left(\lambda_{+}-0\right)-J\left(\lambda_{-}-0\right)+\left.\varepsilon \frac{\partial S(J(\lambda), \Psi(\lambda), \lambda)}{\partial T}\right|_{\lambda_{-}+0} ^{\lambda_{+}-0} \tag{3.2}
\end{equation*}
$$

and the assertion of Sect. 2 concerning the accuracy of (2.5) yields

$$
J\left(\lambda_{+}-0\right)-J\left(\lambda_{-}+0\right)=O\left(\mathrm{E}^{n+1}\right)
$$

Analysis of the procedure of sect. 2 shows that

$$
S\left(I, \varphi, \lambda_{ \pm} \mp 0\right)=\frac{\varepsilon^{n-1}}{\omega^{n}\left(I, \lambda_{ \pm}\right)}\left(\frac{\partial^{n-1}}{\partial \lambda^{n-1}} L^{n} H_{1}\right)_{\lambda=\lambda_{ \pm} \mp 0}
$$

Let us now substitute the above expression into the right-hand part of (3.2) and replace in $S J(\lambda)$ by $I_{-}$and $\varphi\left(\lambda_{+}\right)$by $\varphi_{*}\left(\lambda_{+}\right)$. The admissible error in this case is $O\left(\varepsilon^{n+1}\right)$. Taking into account the expression for $H_{1}$ (1.3), we obtain the required expression (3.1).

Note. The formula (3.1) can be rewritten in the form

$$
\Delta I=-\int_{\lambda}^{\lambda_{+}} \frac{\partial H_{1}\left(\lambda_{-,} \varphi_{*}(\lambda), \lambda\right)}{\partial \varphi} d \lambda+O\left(e^{n+1}\right)
$$

since the asymptotics of the integral is given here by the right-hand part of (3.1).
4. Exponential estimate of the variation of the adiabatic invariant for an analytic perturbation. Let now the function $\xi(\lambda)$ be analytic in some strip $|\operatorname{lm} \lambda|<\rho$. Let also the integral

$$
\begin{equation*}
\int_{-x}\left|\frac{d \bar{\zeta}}{d \lambda}\right| d \lambda \tag{4.1}
\end{equation*}
$$

be uniformly bounded in this strip for the straight lines $\operatorname{Im} \lambda=$ const and let $d \xi / d \lambda \rightarrow 0$ as $\operatorname{Re} \lambda \rightarrow \pm \infty$. We shall assume, as before, that the initial Hamiltonian $E(p, q, \xi)$ is an analytic function of its arguments, so that the passage to the action-angle variables yields the Hamiltonian $H$ (1.2) analytic in the complex domain

$$
|\operatorname{Im} \lambda|<\rho, \quad\left|I-I_{0}\right|<x, \quad|\operatorname{Im} \varphi|<\sigma
$$

where $x>0, \sigma>0, I_{0}$ are constants and $I_{0}$ is real.
Let $I(\lambda), \varphi(\lambda)$ be the solution of the Hamiltonian system in question, and $I(0)=I_{0}$. The convergence of the integral (4.1) implies the existence of

$$
I_{ \pm}=\lim _{\lambda \rightarrow \pm \infty} I(\lambda), \quad \Delta I=I_{+}-I_{-}
$$

Theorem 2. The variation of the adiabatic invariant $\Delta l$ is exponentially small: $\Delta I=$ $O\left(\exp \left(-c_{1} / \varepsilon\right)\right), c_{1}>0$ is a constant.

Proof. This is based on the procedure of Sect. 3 and uses the technique of estimates given in $/ 7,8 /$. After a large number of steps ( $\sim 1 / \varepsilon$ ) of the procedure, the dependence of the Hamiltonian on phase concentrates in the exponentially small terms, and this implies the exponential smallness of $\Delta I$.

Let us pass to the estimates. We denote by $\rho_{0}, \chi_{0}, \sigma_{0}, \vartheta, \Theta, M_{0}$ the positive constants such, that when

$$
|\operatorname{Im} \lambda|<\rho_{0}, \quad\left|I-I_{0}\right|<x_{0}, \quad|\operatorname{Im} \varphi|<\sigma_{0}
$$

then the inequalities

$$
\begin{equation*}
\theta<\left|\partial H_{0} / \partial I\right|<\theta, \quad\left|H_{1}\right|<M_{0} \tag{4.2}
\end{equation*}
$$

nold.
Consider the procedure of sect.2. Let us carry out $N \geqslant 0$ steps of this procedure. After the $k$-th step the Hamiltonian is reduced to the form

$$
\Phi(k)(I, \varphi, \lambda)=\Phi_{0}^{(k)}(I, \lambda)+\varepsilon \Phi_{1}^{(k)}(I, \varphi, \lambda),\left\langle\Phi_{1}^{(k)}\right\rangle^{\Phi}=0, \quad\left|\Phi_{1}^{(k)}\right|<M_{k}=M_{k}(\varepsilon)
$$

in the region

$$
\begin{align*}
& |\operatorname{Im} \lambda|<\rho_{k}, \quad\left|I-I_{0}\right|<x_{k}, \quad|\operatorname{Im} \varphi|<\sigma_{k}  \tag{4.3}\\
& \rho_{k}=\rho_{0}-k \Delta, \quad x_{k}=x_{0}-4 \sum_{i=1}^{k} \delta_{i}, \quad \sigma_{k}=\sigma_{0}-4 \sum_{i=1}^{k} \beta_{i} \\
& \delta_{i}=2^{-i} \delta, \quad \beta_{i}=2^{-i} \beta, \quad \delta=1 / \mathrm{g}_{0}, \quad \beta=1 / \mathrm{s} \sigma_{0}
\end{align*}
$$

We shall show that be choosing suitably $\Delta=\Delta(\varepsilon), M_{i}=M_{i}(\varepsilon)$ we can obtain $N \sim 1 / \varepsilon$ such, that the following estimates will hold at all steps of the procedure:

$$
\begin{gather*}
1 / 2_{2}<\left|\partial \Phi_{0}(i) / \partial I\right|<2 \theta  \tag{4.4}\\
\frac{\varepsilon M_{i}}{\delta_{i+1}}<\frac{\theta}{2}, \frac{\varepsilon M_{i}}{\delta_{i+1} \beta_{i+1}}<\frac{\theta}{\pi}, \frac{\Delta M_{i}}{\delta_{i+1}}<\frac{\pi \theta}{2 \theta} \tag{4.5}
\end{gather*}
$$

The proof is by induction. The estimates (4.4) and (4.5) clearly hold for the initial Hamiltonian. Assume that they hold for $k$ steps and, that $\rho_{k+1}=\rho_{k}-\Delta>0$. Consider now the $(k+1)$-th step, denoting the new variables by $J$ and $\psi$. The generating function of the variable change $W$ has the form

$$
\begin{equation*}
W=J \varphi+\varepsilon S(J, \varphi, \lambda), \quad \frac{\partial S}{\partial \Phi}=-\frac{\Phi_{1}^{(\alpha)}}{\partial \Phi_{0}^{(k)} / \partial I},\langle S\rangle^{\varphi}=0 \tag{4.6}
\end{equation*}
$$

Using the assumptions (4.4) and (4.5) we can show that when

$$
\left|I-I_{0}\right|<x_{k}-2 \delta_{k_{+1}}, \quad|\operatorname{Im} \varphi|<\sigma_{k}-2 \beta_{k+1}
$$

the change governed by the generating function $W$ is well defined and the domain of variation of the new variables $J, \psi$ contains the region

$$
\left|J-I_{0}\right|<x_{k}-3 \delta_{k+1}, \quad|\operatorname{Im} \psi|<\sigma_{k}-3 \beta_{k+1}
$$

The proof duplicates the known argument of (/7/, Sect.4) and is therefore omitted.
Let us obtain the estimates for the new Hamiltonian. Using the Cauchy inequalities $/ 7 /$, the definition of $S(4.6)$ and the estimates (4.4), (4.5) we find that when
$|\operatorname{Im} \lambda|<\rho_{k}-\Delta, \quad\left|I-I_{0}\right|<x_{k}-2 \delta_{k+1}, \quad|\operatorname{Im} \varphi|<\sigma_{k}$
then the inequalities

$$
\begin{equation*}
\left|\frac{\partial \Phi_{1}^{(k)}}{\partial I}\right|<\frac{M_{k}}{2 \delta_{k+1}},\left|\frac{\partial \mu \Phi_{0}^{(k)}}{\partial I^{2}}\right|<\frac{\theta}{\delta_{k+1}},\left|\frac{\partial S}{\partial \varphi}\right|<\frac{2 M_{k}}{\theta}, \quad|S|<\frac{2 \pi M_{k}}{\theta},\left|\frac{\partial S}{\partial \lambda}\right|<\frac{2 \pi M_{k}}{\Delta \theta} \tag{4.7}
\end{equation*}
$$

hold. The new Hamiltonian is computed according to 2.2 ). Estimating the right-hand part of (2.3) in the region

$$
|\operatorname{Im} \lambda|<\rho_{k}-\Delta,\left|J-I_{0}\right|<x_{k}-3 \delta_{k+1}, \quad|\operatorname{Im} \varphi|<\sigma_{k}
$$

we find, with the help of (4.4), (4.5) and (4.7), that

$$
|\varepsilon F|<e\left(\frac{2 \pi M_{k}}{\Delta \theta}+\frac{M_{k}^{2}}{\delta_{k+1}^{\theta}}+\frac{2 M_{k}^{2} \theta}{\delta_{k+1} \theta^{\theta}}\right)=\frac{2 \pi e M_{k}}{\Delta \theta}\left(1+\frac{\Delta M_{k}}{2 \pi \delta_{k+1}}+\frac{\Delta M_{k} \theta}{\pi \delta_{k+1}^{\theta} \theta}\right)<\frac{4 \pi e M_{k}}{\Delta \theta}
$$

and this yields

$$
\begin{equation*}
\left|\Phi_{1}^{(k+1)}\right|=\left|\{e F\}^{\psi}\right|<\frac{8 \pi e M_{k}}{\Delta \theta} \tag{4.8}
\end{equation*}
$$

$$
\begin{equation*}
\left|\Phi_{0}^{(k)}-\Phi_{0}^{(l+1)}\right|=\left|\left\langle\varepsilon^{2} F\right\rangle^{\Psi}\right|<\frac{4 \pi \varepsilon^{2} M_{k}}{\Delta \theta} \tag{4.9}
\end{equation*}
$$

Expression (4.9) and the Cauchy inequality together show that when $\left|J-I_{0}\right|<x_{k}-4 \delta_{k+1}$ then

$$
\begin{equation*}
\left|\frac{\partial \Phi_{0}^{(i)}}{\partial J}-\frac{\partial \Phi_{0}^{(l+1)}}{\partial,}\right|<\frac{4^{4} \pi \varepsilon^{2} M_{k}}{\Delta \theta \delta_{k+1}} \tag{4.10}
\end{equation*}
$$

Let us write

$$
\begin{equation*}
\Delta=\frac{32 \pi}{\theta} \varepsilon, \quad M_{k+1}=\frac{8 \pi \varepsilon}{\Delta \theta} M_{k}=1 / 1 / M_{\dot{\kappa}} \tag{4.11}
\end{equation*}
$$

Then

$$
\begin{equation*}
M_{i}=\left(\frac{1}{4}\right)^{i} M_{0}, \quad \frac{M_{i}}{\delta_{i+1}}=\left(\frac{1}{2}\right)^{i-1} \frac{M_{n}}{\delta}, \frac{M_{i}}{\delta_{i+1} \beta_{i+1}}=\frac{4 M_{0}}{\delta \bar{p}}, \quad 0 \leqslant i \leqslant k+1 \tag{4.12}
\end{equation*}
$$

and from this it is clear that the relations (4.5) remain valid for the $(k+1)$-th step of the procedure. Further, from (4.2) and (4.10)-(4.12) we obtain

$$
\left|\frac{\partial \Phi_{0}^{(k+1)}}{\partial J}\right|>\vartheta-1 / \iota \varepsilon \sum_{i=0}^{k}\left(\frac{1}{2}\right)^{i} \frac{M_{0}}{\delta}>\vartheta-\frac{\varepsilon M_{0}}{2 \delta}, \quad\left|\frac{\partial \Phi_{0}^{(k+1)}}{\partial J}\right|<\Theta \ldots \frac{\varepsilon M_{0}}{2 \delta}
$$

Since $\delta=1 /{ }_{8} \chi=$ const it follows that for a sufficiently small $\varepsilon$ the conditions (4.4) hold also for the $(k+1)$-th step.

In this manner we can repeat the variable change as long as $\rho_{k}>0$. This means that we can carry out

$$
N=\left\lfloor\frac{\rho_{0}}{\delta}\right\rceil \geqslant \frac{\rho_{0} \theta}{32 \pi \varepsilon}-1
$$

steps. After the $N$-th step we obtain

$$
\left|\Phi_{1}^{(N)}\right|<M_{0}\left(\frac{1}{4}\right)^{N}=O\left(\exp \left(-c_{1} / \varepsilon\right)\right)
$$

i.e. $\Phi_{1}^{(N)}$ is an exponentially small quantity.

We shall show that the function $\Phi_{1}^{(N)}$ is also exponentially small on the integral norm

$$
\left\|\Phi_{i}^{(k)}\right\|=\sup _{|\operatorname{Im} \lambda|<\rho_{k}} \int_{-\infty}^{\infty} \sup _{I, \varphi}\left|\Phi_{i}^{(k)}\right| d \lambda
$$

where the upper bound of the integrand is taken over all $I$ and $\varphi$ belonging to the domain of definition of $\Phi_{1}^{(k)}$ (4.2), the integral is taken along the straight line $\operatorname{Im} \lambda=$ const, and the upper bound preceding the integral is taken over all such lines with $|\operatorname{Im} \lambda|<\rho_{k}$.

Let us return to the $(k+1)$-th step of the procedure of sect.2. We shall obtain the estimate for the integral norm of the function $\partial S / \partial \lambda$ in the strip $|\operatorname{Im} \lambda|<\rho_{k+1}=\rho_{k}-\Delta$ in terms of the integral norm of $S$ in the strip $|\operatorname{Im} \lambda|<p_{k}$. In order to simplify the formula, we shall write, for the time being, $S(\lambda)=S(I, \varphi, \lambda)$. By virtue of the Cauchy integral formula we have

$$
\frac{\partial S}{\partial \lambda}=\frac{1}{2 \pi i} \oint_{\Gamma} \frac{S(\lambda+\zeta)}{\zeta^{2}} d \zeta
$$

where the contour $\Gamma$ is a circle of radius $\Delta$ with the center at the point 0 . Therefore

$$
\left\|\frac{\partial S}{\partial \lambda}\right\|=\frac{1}{2 \pi} \sup _{|\mathrm{Im} \lambda|<\rho_{k+1}} \int_{-\sim 1} \sup _{\boldsymbol{I}, \varphi}\left|\oint_{\Gamma} \frac{S(\lambda,-\zeta)}{\zeta^{2}} d \zeta\right| d \lambda
$$

Changing the order of integration, we obtain

$$
\left\|\frac{\partial S}{\partial \lambda}\right\| \leqslant \frac{1}{2 \pi} \oint_{\Gamma}\left(\sup _{|\operatorname{Im} \lambda|<\rho_{k+1}} \int_{-\infty}^{\approx} \sup _{I, \varphi}|S(\lambda-\zeta)| d \lambda\right) \frac{|d \Sigma|}{|5|^{2}}=\frac{\|s\|}{2 \pi} \oint_{\Gamma} \frac{\left|d_{5}^{2}\right|}{|s|^{2}}=\frac{\|S\|}{\Delta}
$$

Estimatina now $\|S\|$ is terms of $\|\Phi\|_{i}^{(i)} \|$ and using (4.4), (4.6) we find, that at the
$(k+1)$-th step of the procedure

$$
\begin{equation*}
\left\|\frac{\partial S}{\partial \lambda} \left\lvert\, \leqslant \frac{2 \pi}{\Delta \theta}\right.\right\| \Phi_{1}^{(k)} \| \tag{4.13}
\end{equation*}
$$

Finally, estimating $\left\|\Phi_{i}^{(k+1)}\right\|$ and using (2.3), (4.13), (4.4), (4.5), (4.7) and (4.11), we obtain

$$
\left\|\Phi_{i}^{(k+1)}\right\| \leqslant{ }^{1 /+}\left\|\Phi_{1}^{(k)}\right\|
$$

Therefore

$$
\left\|\Phi_{1}^{(N)}\right\| \leqslant\left(\frac{1}{4}\right)^{N}\left\|H_{1}\right\|=O\left(\exp \left(-\frac{c_{1}}{r}\right)\right) \sup _{|\mathrm{Im} \lambda|<\rho} \int_{-\infty}^{\infty}\left|\frac{d \xi}{d \lambda}\right| d \lambda=O\left(\exp \left(-\frac{c_{1}}{\varepsilon}\right)\right)
$$

## Q.E.D.

Let us now study the variation of the adiabatic invariant over an infinite period. Let us denote by $J, \psi$ the variables introduced at the $N$-th step of the procedure. The domain of variation of these variables contains the region

$$
\left|J-I_{0}\right|<1 / 2 x_{0}, \quad|\operatorname{Im} \psi|<\frac{1 / 2}{2} \sigma_{0}
$$

Let $J(\lambda), \psi(\lambda)$ denote the initial solution $I(\lambda), \varphi(\lambda)$ in terms of the variables $J . \psi$. Since $d \xi / d \lambda \rightarrow 0$ as $\lambda \rightarrow \pm \infty$, the substitution $I, \varphi \rightarrow J, \psi$ tends to become an indentity when $\lambda \rightarrow \pm \infty$. This implies that

$$
J_{ \pm}=\lim J(\lambda) \text { when } \lambda \rightarrow \pm \infty, J_{ \pm}=I_{ \pm}
$$

exist. Now,

$$
\Delta I=J_{+}-J_{-}=-\int_{-\infty}^{\infty} \frac{\partial \Phi_{1}^{(N)}(I(\lambda), \psi(\lambda), \lambda)}{\partial \psi} d \lambda
$$

By virtue of the Cauchy inequality we have, for real $\psi$,

$$
\left|\frac{\partial \Phi_{1}^{(N)}}{\partial \psi}\right| \leqslant \frac{2}{J_{0}} \sup _{\operatorname{Im} \psi \mid<1 ; \sigma_{0}}\left|\Phi_{1}^{(N)}\right|
$$

and this yields

$$
\Delta I=O\left(\|\left(\mathrm{D}_{1}(\cdot) \|\right)=O\left(\exp \left(-c_{1} / \varepsilon\right)\right)\right.
$$

Q.E.D.

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