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ON THE ACCURACY OF CONSERVATION OF THE ADIABATIC INVARIANT*

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A Hamiltonian system with one degree of freedom is considered. The system depends on the parameter ξ which varies slowly with time $t: \xi = \xi(\varepsilon t), 0 < \varepsilon \ll 1$ and tends in a sufficiently regular manner to well defined limits as $t \to \pm \infty$. When $t \to \pm \infty$, the adjabatic invariant, acting along the trajectory of such system, has the limit meanings I_+ . Their difference $\Delta I = I_+ - I_-$ is estimated.

The problem of estimating ΔI appears in classical mechanics /1,2/, quantum mechanics /3/ and in the theory of waveguides /4/. In the case when the dependence of ξ on εt is finite ($\xi(\varepsilon t) = \operatorname{const}$ for sufficiently large εt) and infinitely differentiable, the author of /5/ shows that ΔI decreases, as $\varepsilon \to 0$, faster than any power of ε . For the linear systems with the frequency depending analytically on εt , the known asymptotic of ΔI is found to be exponential $\Delta I = 0 (\exp(-c/\varepsilon)), c = \operatorname{const} /3, 6/$. An erroneous proof of the exponential smallness of ΔI in given in /1/ for the case of an analytic $\xi(\varepsilon t)$ for the general nonlinear systems.

Below the problem of estimating ΔI is considered with help of the perturbations procedure in the action-angle variables. For the case when the dependence of ξ on ϵt is finite and has a finite smoothness, a power asymptotics is obtained for ΔI and the exponential smallness of ΔI in ϵ is proved for the case of analytic $\xi(\epsilon t)$.

1. Equations in the action-angle variables. The Hamiltonian of the problem in question has the form

$$E = E(p, q, \xi), \quad \xi = \xi(\lambda), \quad \lambda = \varepsilon t \tag{1.1}$$

where p and q denote the canonical variables. We assume that E is an analytic function of p, q and ξ .

Let a region filled with closed trajectories exist for every ξ on the phase plane of the unperturbed ($\xi = \text{const}$) problem. The action—angle variables of the unperturbed problem are defined in this region /1/. The action $I = I(p, q, \xi)$ is an area divided by 2π , bounded by an unperturbed trajectory passing through the point (p, q). The angle $\varphi = \varphi(p, q, \xi) \mod 2\pi$ is an angular coordinate along the trajectory, varying uniformly in the unperturbed system. The variable change $p, q \rightarrow I, \varphi$ is canonical and time-dependent. The change of the variables I, φ in the initial problem is described by a Hamiltonian system with the Hamiltonian

$$H(I, \varphi, \lambda) = H_0(I, \lambda) + \varepsilon H_1(I, \varphi, \lambda)$$
(1.2)

where H_{0} is the original Hamiltonian of E expressed in terms of I and λ

$$H_{1} = (d\xi/d\lambda) G (I, \varphi, \lambda)$$

$$G = \frac{1}{\omega} \left[-\int_{0}^{\varphi} \frac{\partial E}{\partial \xi} d\varphi + \frac{\varphi}{2\pi} \int_{0}^{2\pi} \frac{\partial E}{\partial \xi} d\varphi \right]$$

$$\omega = \omega (I, \lambda) = \partial H_{0}/dI$$
(1.3)

and H is an analytic function of I and φ , and 2π -periodic in φ .

We shall use the angle brackets $\langle \cdot \rangle^{\varphi}$ for the 2π -periodic functions of φ to denote the averaging over φ , and the curly brackets $\{\cdot\}^{\varphi}$ for the purely periodic part: $\{\cdot\}^{\varphi} = (\cdot) - \langle \cdot \rangle^{\varphi}$. Further, in order to reduce the amount of notations used we shall assume that $\langle H_1 \rangle^{\varphi} = 0$, otherwise we shall have to replace, in the arguments that follow, H_0 by $H_0 + \varepsilon \langle H_1 \rangle^{\varphi}$, and H_1 by $\{H_1\}^{\varphi}$.

2. The procedure of the perturbation theory. The procedure described here of asymptotic integration of the system with the Hamiltonian (1.2), analogous to that given in /7/, will be used to obtain the estimates of variation in the value of the adiabatic invariant.

Let us carry out, in the system with the Hamiltonian (1.2), a canonical, nearly identical variable transformation with a so far undefined generating function $W = J\varphi + \varepsilon S (J, \varphi, \lambda)$. Here J and ψ are the new canonical variables connected with I and φ by the relations

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$$I = J + \varepsilon \frac{\partial S}{\partial \varphi}, \quad \psi = \varphi + \varepsilon \frac{\partial S}{\partial J}$$
(2.1)

The variation in J and ψ is described by a Hamiltonian system with the Hamiltonian

$$\Phi(J, \psi, \lambda) = \varepsilon^2 \frac{\partial S}{\partial \lambda} + H_0 \Big(J + \varepsilon \frac{\partial S}{\partial \varphi} \Big) + \varepsilon H_1 \Big(J + \varepsilon \frac{\partial S}{\partial \varphi} , \varphi, \lambda \Big)$$
(2.2)

In the right-hand part of (2.2) φ must be expressed in terms of J and ψ in accordance with (2.1). Let us choose

$$S = \frac{1}{\partial H_0/\partial I} \left\{ \int_0^{\varphi} H_1 d\varphi \right\}^{\varphi}$$

Since $\langle H_1 \rangle^{\varphi} = 0$, the above expression is correct and S is a 2π -periodic function of φ with a zero mean value. For S chosen in such a manner we have

$$\Phi = H_0 (J, \lambda) + \varepsilon^2 F$$

$$\varepsilon^2 F = \varepsilon^2 \frac{\partial S}{\partial \lambda} + \left(H_0 \left(J + \varepsilon \frac{\partial S}{\partial \varphi} , \lambda \right) - H_0 (J, \lambda) - \varepsilon \frac{\partial H_0 (J, \lambda)}{\partial J} \frac{\partial S}{\partial \varphi} \right) + \varepsilon \left(H_1 \left(J + \varepsilon \frac{\partial S}{\partial \varphi} , \varphi, \lambda \right) - H_1 (J, \varphi, \lambda) \right), \quad F = O(1)$$
(2.3)

Let us denote

$$\Phi_0 = H_0 + e^2 \langle F \rangle^{\psi}, \quad \Phi_1 = \{F\}^{\psi}$$

Then the Hamiltonian will become

$$\Phi = \Phi_{\mathbf{0}} (J, \lambda) + \varepsilon^2 \Phi_{\mathbf{1}} (J, \psi, \lambda)$$

which is completely analogous to (1.2) except that the term depending on the phase ψ is now of the order of ε^3 . Repeating the above procedure once more, we obtain a Hamiltonian in which the phase dependence appears only in the terms of the order of ε^3 . Finally, after *n* steps of the above procedure we obtain the Hamiltonian in the form

$$\Phi (J, \psi, \lambda) = \Phi_0 (J, \lambda) + \varepsilon^{n+1} \Phi_1 (J, \psi, \lambda)$$
(2.4)

where the new variables and the Hamiltonian are still expressed in terms of J, ψ and Φ . Neglecting in the Hamiltonian (2.4) the last term, we obtain the following relations for

the variation of J and ψ with time:

$$J = \text{const.} \quad \psi = \psi_0 + \frac{1}{\varepsilon} \int_{\lambda_0}^{\lambda} \frac{\partial \Phi_0(J, v)}{\partial J} dv, \quad \psi_0 = \text{const}$$
(2.5)

Analysis of the corrections brought in by each consecutive step of the procedure shows that the relations (2.5) describe the variation in J with the accuracy of $O(\varepsilon^{n+1})$ and in ψ with the accuracy of $O(\varepsilon^n)$ on the time intervals of the order $1/\varepsilon$ (provided that the step in question is feasible). From (2.3) we see that every step of the procedure reduces the smoothness of the Hamiltonian with respect to λ , by 1. It follows therefore that the number of steps which can be carried out depends on the smoothness H of the Hamiltonian with respect to λ .

3. The asymptotics of variation of the adiabatic invariant for a finite perturbation of finite smoothness. Let the perturbation be finite $\xi(\lambda) \equiv \text{const}$ for $\lambda < \lambda_{-}$ and $\lambda > \lambda_{+}$, where λ_{\pm} are constant. Let the first n-1 derivatives of $\xi(\lambda)$ be continuous (and hence vanish) at the point λ_{\pm} , and the *n*-th derivative be discontinuous, i.e. n > 1. Let the function $\xi(\lambda)$ be differentiable n + 2 times for $\lambda \in (\lambda_{-}, \lambda_{+})$ and its derivatives bounded. We shall calculate the asymptotics of variation of the adiabatic invariant.

Let us denote by $I(\lambda)$, $\varphi(\lambda)$ the solution of a system with the Hamiltonian (1.2) and $I_{\pm} = I(\lambda_{\pm})$, $\varphi_{-} = \varphi(\lambda_{-})$, $\Delta I = I_{+} - I_{-}$. We shall write, for a 2π -periodic function $f(\varphi)$ with zero mean value

$$(Lf)(\varphi) = -\left\{\int_{0}^{\varphi} f(\gamma) \, d\gamma\right\}^{\Phi}$$

Theorem 1. The quantity ΔI has the following asymptotics

$$\Delta I = \varepsilon^{n} \left(R \left(\lambda_{+} - 0 \right) - R \left(\lambda_{-} + 0 \right) \right) + O \left(\varepsilon^{n+1} \right), \quad R(\lambda) = - \frac{\xi^{(n)}(\lambda)}{\omega^{n} \left(I_{-}, \lambda \right)} \left(L^{n-1} G \right) \left(I_{-}, \varphi_{*}(\lambda), \lambda \right)$$
(3.1)

where L^{n-1} denotes the operator L raised to the (n-1)-th power, G is given by (1.3), and

$$\varphi_{\mathbf{*}}(\lambda) = \varphi_{-} + \varepsilon^{-1} \int_{\lambda_{-}}^{\lambda} \omega \left(I_{-} + \varepsilon \frac{H_{1}(I_{-}, \varphi_{-}, \lambda_{-} + 0)}{\omega(I_{-}, \lambda_{-})} , v \right) dv$$

Proof. When $\lambda \in (\lambda_-, \lambda_+)$, the smoothness allows n + 1 steps of the procedure given in Sect.2. Let us denote by (J, ψ) the variables introduced in the *n*-th step, and by $W = J\varphi + \varepsilon S(J, \varphi, \lambda)$ the generating function of the substitution $(I, \varphi) \to (J, \psi)$. Let $J(\lambda), \psi(\lambda)$ denote the solution $I(\lambda), \varphi(\lambda)$ in terms of the variables (J, ψ) . From the formulas for the substitution of variables it follows that

$$I(\lambda_{+}) - I(\lambda_{-}) = J(\lambda_{+} - 0) - J(\lambda_{-} - 0) + e \frac{\partial S(J(\lambda), \varphi(\lambda), \lambda)}{\partial \varphi} \Big|_{\lambda_{+} = 0}^{\lambda_{+} - 0}$$
(3.2)

and the assertion of Sect.2 concerning the accuracy of (2.5) yields

$$J (\lambda_{+} - 0) - J (\lambda_{-} + 0) = O (\varepsilon^{n+1})$$

Analysis of the procedure of Sect.2 shows that

$$S(I, \varphi, \lambda_{\pm} \mp 0) = \frac{\varepsilon^{n-1}}{\omega^n (I, \lambda_{\pm})} \left(\frac{\partial^{n-1}}{\partial \lambda^{n-1}} L^n H_1 \right)_{\lambda = \lambda_{\pm} \mp 0}$$

Let us now substitute the above expression into the right-hand part of (3.2) and replace in $S J(\lambda)$ by I_- and $\varphi(\lambda_+)$ by $\varphi_*(\lambda_+)$. The admissible error in this case is $O(e^{n+1})$. Taking into account the expression for H_1 (1.3), we obtain the required expression (3.1).

Note. The formula (3.1) can be rewritten in the form

$$\Delta I = -\int_{\lambda_{-}}^{\lambda_{+}} \frac{\partial H_{1}\left(I_{-}, \varphi_{*}(\lambda), \lambda\right)}{\partial \varphi} d\lambda + O\left(\varepsilon^{n+1}\right)$$

since the asymptotics of the integral is given here by the right-hand part of (3.1).

4. Exponential estimate of the variation of the adiabatic invariant for an analytic perturbation. Let now the function $\xi(\lambda)$ be analytic in some strip $|Im\lambda| < \rho$. Let also the integral

$$\int_{-\infty}^{\infty} \left| \frac{d\xi}{d\lambda} \right| d\lambda \tag{4.1}$$

be uniformly bounded in this strip for the straight lines $\operatorname{Im} \lambda = \operatorname{const}$ and let $d\xi/d\lambda \to 0$ as $\operatorname{Re} \lambda \to \pm \infty$. We shall assume, as before, that the initial Hamiltonian $E(p, q, \xi)$ is an analytic function of its arguments, so that the passage to the action-angle variables yields the Hamiltonian H(1.2) analytic in the complex domain

$$|\operatorname{Im} \lambda| < \rho, |I - I_0| < \varkappa, |\operatorname{Im} \varphi| < \sigma$$

where x > 0, $\sigma > 0$, I_0 are constants and I_0 is real.

Let $I(\lambda), \varphi(\lambda)$ be the solution of the Hamiltonian system in question, and $I(0) = I_0$. The convergence of the integral (4.1) implies the existence of

$$I_{+} = \lim_{\lambda \to \pm \infty} I(\lambda), \quad \Delta I = I_{+} - I_{-}$$

Theorem 2. The variation of the adiabatic invariant ΔI is exponentially small: $\Delta I = O(\exp(-c_1/\epsilon)), c_1 > 0$ is a constant.

Proof. This is based on the procedure of Sect.3 and uses the technique of estimates given in /7,8/. After a large number of steps ($\sim 1/\epsilon$) of the procedure, the dependence of the Hamiltonian on phase concentrates in the exponentially small terms, and this implies the exponential smallness of ΔI .

Let us pass to the estimates. We denote by $\rho_0, \varkappa_0, \sigma_0, \vartheta, \Theta, M_0$ the positive constants such, that when

 $|\operatorname{Im} \lambda| < \rho_0, \quad |I - I_0| < \varkappa_0, \quad |\operatorname{Im} \varphi| < \sigma_0$

then the inequalities

$$\vartheta < |\partial H_0/\partial I| < \Theta, |H_1| < M_0$$
(4.2)

hold.

Consider the procedure of Sect.2. Let us carry out $N \ge 0$ steps of this procedure. After the k-th step the Hamiltonian is reduced to the form

$$\Phi^{(k)}(I, \varphi, \lambda) = \Phi_0^{(k)}(I, \lambda) + \varepsilon \Phi_1^{(k)}(I, \varphi, \lambda), \quad \langle \Phi_1^{(k)} \rangle^{\varphi} = 0, \quad |\Phi_1^{(k)}| < M_k = M_k (\varepsilon)$$

in the region

$$|\operatorname{Im} \lambda| < \rho_{k}, \quad |I - I_{0}| < \varkappa_{k}, \quad |\operatorname{Im} \varphi| < \sigma_{k}$$

$$\rho_{k} = \rho_{0} - k\Delta, \quad \varkappa_{k} = \varkappa_{0} - 4\sum_{i=1}^{k} \delta_{i}, \quad \sigma_{k} = \sigma_{0} - 4\sum_{i=1}^{k} \beta_{i}$$

$$\delta_{i} = 2^{-i}\delta, \quad \beta_{i} = 2^{-i}\beta, \quad \delta = \frac{1}{8}\kappa_{0}, \quad \beta = \frac{1}{8}\sigma_{0}$$

$$(4.3)$$

We shall show that be choosing suitably $\Delta = \Delta(\epsilon)$, $M_i = M_i(\epsilon)$ we can obtain $N \sim 1/\epsilon$ such, that the following estimates will hold at all steps of the procedure:

$$\frac{1}{2\theta} < |\partial \Phi_0^{(i)}/\partial I| < 2\Theta$$
(4.4)

$$\frac{\varepsilon M_{i}}{\delta_{i+1}} < \frac{\vartheta}{2}, \quad \frac{\varepsilon M_{i}}{\delta_{i+1}\beta_{i+1}} < \frac{\vartheta}{\pi}, \quad \frac{\Delta M_{i}}{\delta_{i+1}} < \frac{\pi \vartheta}{2\Theta}$$
(4.5)

The proof is by induction. The estimates (4.4) and (4.5) clearly hold for the initial Hamiltonian. Assume that they hold for k steps and, that $\rho_{k+1} = \rho_k - \Delta > 0$. Consider now the (k + 1)-th step, denoting the new variables by J and ψ . The generating function of the variable change W has the form

$$W = J\varphi + \varepsilon S(J, \varphi, \lambda), \quad \frac{\partial S}{\partial \varphi} = - \frac{\Phi_1^{(k)}}{\partial \Phi_1^{(k)} / \partial I}, \quad \langle S \rangle^{\varphi} = 0$$
(4.6)

Using the assumptions (4.4) and (4.5) we can show that when

$$|I - I_0| < \varkappa_k - 2\delta_{k+1}, \quad |\operatorname{Im} \varphi| < \sigma_k - 2\beta_{k+1}$$

the change governed by the generating function W is well defined and the domain of variation of the new variables J, ψ contains the region

$$|J - I_0| < \varkappa_k - 3\delta_{k+1}, \quad |\operatorname{Im} \psi| < \sigma_k - 3\beta_{k+1}$$

The proof duplicates the known argument of (/7/,Sect.4) and is therefore omitted.

Let us obtain the estimates for the new Hamiltonian. Using the Cauchy inequalities /7/, the definition of S (4.6) and the estimates (4.4), (4.5) we find that when

$$|\operatorname{Im} \lambda| < \rho_k - \Delta, \quad |I - I_0| < \varkappa_k - 2\delta_{k+1}, \quad |\operatorname{Im} \varphi| < \sigma_k$$

then the inequalities

$$\left|\frac{\partial \Phi_{1}^{(k)}}{\partial I}\right| < \frac{M_{k}}{2\delta_{k+1}}, \quad \left|\frac{\partial \Phi_{0}^{(k)}}{\partial I^{2}}\right| < \frac{\Theta}{\delta_{k+1}}, \quad \left|\frac{\partial S}{\partial \varphi}\right| < \frac{2M_{k}}{\Theta}, \quad |S| < \frac{2\pi M_{k}}{\Theta}, \quad \left|\frac{\partial S}{\partial \lambda}\right| < \frac{2\pi M_{k}}{\Delta \Theta}$$
(4.7)

hold. The new Hamiltonian is computed according to (2.3). Estimating the right-hand part of (2.3) in the region

 $|\operatorname{Im} \lambda| < \rho_k - \Delta, |J - I_0| < \varkappa_k - 3\delta_{k+1}, |\operatorname{Im} \varphi| < \sigma_k$

we find, with the help of (4.4), (4.5) and (4.7), that

$$|\varepsilon F| < \varepsilon \left(\frac{2\pi M_k}{\Delta \vartheta} + \frac{M_k^3}{\delta_{k+1} \vartheta} + \frac{2M_k^2 \vartheta}{\delta_{k+1} \vartheta^3} \right) = \frac{2\pi e M_k}{\Delta \vartheta} \left(1 + \frac{\Delta M_k}{2\pi \delta_{k+1}} + \frac{\Delta M_k \vartheta}{\pi \delta_{k+1} \vartheta} \right) < \frac{4\pi e M_k}{\Delta \vartheta}$$

and this yields

$$|\Phi_1^{(k+1)}| = |\{eF\}^{\psi}| < \frac{8\pi eM_k}{\Delta \Phi}$$
(4.8)

$$|\Phi_0^{(k)} - \Phi_0^{(k+1)}| = |\langle e^2 F \rangle^{\psi}| < \frac{\ell_{\pi e^2 M_k}}{\Delta \vartheta}$$
(4.9)

Expression (4.9) and the Cauchy inequality together show that when $|J - I_0| < x_k - 4\delta_{k+1}$ then

$$\left|\frac{\partial \Phi_{0}^{(k)}}{\partial J} - \frac{\partial \Phi_{0}^{(k+1)}}{\partial J}\right| < \frac{\lambda_{\pi k^{2}} M_{k}}{\Delta \vartheta \delta_{k+1}}$$
(4.10)

Let us write

$$\Delta = \frac{32\pi}{\vartheta} \varepsilon, \quad M_{k+1} = \frac{8\pi\varepsilon}{\Delta\vartheta} M_k = \frac{1}{4} M_k$$
(4.11)

Then

$$M_{i} = \left(\frac{1}{4}\right)^{i} M_{0}, \quad \frac{M_{i}}{\delta_{i+1}} = \left(\frac{1}{2}\right)^{i-1} \frac{M_{0}}{\delta}, \quad \frac{M_{i}}{\delta_{i+1}\beta_{i+1}} = \frac{4M_{0}}{\delta\beta}, \quad 0 \leqslant i \leqslant k+1$$
(4.12)

and from this it is clear that the relations (4.5) remain valid for the (k + 1) -th step of the procedure. Further, from (4.2) and (4.10)—(4.12) we obtain

$$\left|\frac{\partial \Phi_0^{(k+1)}}{\partial J}\right| > \vartheta - \frac{1}{4\epsilon} \sum_{i=0}^k \left(\frac{1}{2}\right)^i \frac{M_0}{\delta} > \vartheta - \frac{\epsilon M_0}{2\delta}, \quad \left|\frac{\partial \Phi_0^{(k+1)}}{\partial J}\right| < \Theta - \frac{\epsilon M_0}{2\delta}$$

Since $\delta = \frac{1}{8}\kappa = \text{const}$ it follows that for a sufficiently small ϵ the conditions (4.4) hold also for the (k + 1) -th step.

In this manner we can repeat the variable change as long as $\rho_{\bf k}>0$. This means that we can carry out

$$N = \left\lfloor \frac{\rho_0}{\delta} \right\rceil \geqslant \frac{\rho_0 \vartheta}{32\pi\epsilon} - 1$$

steps. After the N-th step we obtain

$$|\Phi_1^{(N)}| < M_0 \left(\frac{1}{4}\right)^N = O\left(\exp\left(-c_1/\varepsilon\right)\right)$$

i.e. $\Phi_1^{(N)}$ is an exponentially small quantity.

We shall show that the function $\Phi_1^{(N)}$ is also exponentially small on the integral norm

$$\|\Phi_1^{(k)}\| = \sup_{|\mathrm{Im}\lambda| < \rho_k} \int_{-\infty}^{\infty} \sup_{I, \varphi} |\Phi_1^{(k)}| d\lambda$$

where the upper bound of the integrand is taken over all I and φ belonging to the domain of definition of $\Phi_1^{(k)}$ (4.2), the integral is taken along the straight line Im $\lambda = \text{const}$, and the upper bound preceding the integral is taken over all such lines with $|\text{Im } \lambda| < \rho_k$.

Let us return to the (k + 1)-th step of the procedure of Sect.2. We shall obtain the estimate for the integral norm of the function $\partial S/\partial \lambda$ in the strip $|\operatorname{Im} \lambda| < \rho_{k+1} = \rho_k - \Delta$ in terms of the integral norm of S in the strip $|\operatorname{Im} \lambda| < p_k$. In order to simplify the formula, we shall write, for the time being, $S(\lambda) = S(I, \varphi, \lambda)$. By virtue of the Cauchy integral formula we have

$$\frac{\partial S}{\partial \lambda} = \frac{1}{2\pi i} \oint \frac{S(\lambda + \zeta)}{\zeta^2} d\zeta$$

where the contour Γ is a circle of radius Δ with the center at the point 0 . Therefore

$$\left\|\frac{\partial S}{\partial \lambda}\right\| = \frac{1}{2\pi} \sup_{|\mathrm{Im}\,\lambda| < \rho_{k+1}} \int_{-\infty}^{\infty} \sup_{I,\Phi} \left| \oint_{\Gamma} \frac{S\left(\lambda - \zeta\right)}{\zeta^{2}} d\zeta \right| d\lambda$$

Changing the order of integration, we obtain

$$\left\|\frac{\partial S}{\partial \lambda}\right\| \leqslant \frac{1}{2\pi} \oint_{\Gamma} \left(\sup_{|\mathrm{Im}\lambda| < \rho_{k+1}} \int_{-\infty}^{\infty} \sup_{I, \phi} |S(\lambda - \zeta)| d\lambda\right) \frac{|d\zeta|}{|\zeta|^2} = \frac{\|S\|}{2\pi} \oint_{\Gamma} \frac{|d\zeta|}{|\zeta|^2} = \frac{\|S\|}{\Delta}$$

Estimating now $\|S\|$ is terms of $\|\Phi_1^{(k)}\|$ and using (4.4), (4.6) we find, that at the

(k + 1)-th step of the procedure

$$\left|\frac{\partial S}{\partial \lambda}\right| \leqslant \frac{2\pi}{\Delta \Phi} \| \Phi_1^{(k)} \| \tag{4.13}$$

Finally, estimating $\|\Phi_1^{(k+1)}\|$ and using (2.3), (4.13), (4.4), (4.5), (4.7) and (4.11), we obtain

$$\|\Phi_1^{(n+1)}\| \leq 1/4 \|\Phi_1^{(n)}\|$$

Therefore

$$\|\Phi_1^{(N)}\| \leq \left(\frac{1}{4}\right)^N \|H_1\| = O\left(\exp\left(-\frac{c_1}{\varepsilon}\right)\right) \sup_{|\operatorname{Im}\lambda| < \rho} \int_{-\infty}^{\varepsilon} \left|\frac{d\xi}{d\lambda}\right| d\lambda = O\left(\exp\left(-\frac{c_1}{\varepsilon}\right)\right)$$

Q.E.D.

Let us now study the variation of the adiabatic invariant over an infinite period. Let us denote by J, ψ the variables introduced at the *N*-th step of the procedure. The domain of variation of these variables contains the region

$$|J - I_0| < \frac{1}{2} \varkappa_0, |Im \psi| < \frac{1}{2} \sigma_0$$

Let $J(\lambda), \psi(\lambda)$ denote the initial solution $I(\lambda), \varphi(\lambda)$ in terms of the variables J, ψ . Since $d\xi/d\lambda \rightarrow 0$ as $\lambda \rightarrow \pm \infty$, the substitution $I, \varphi \rightarrow J, \psi$ tends to become an indentity when $\lambda \rightarrow \pm \infty$. This implies that

$$J_{\pm} = \lim J(\lambda)$$
 when $\lambda \to \pm \infty, J_{\pm} = I_{\pm}$.

exist. Now,

$$\Delta I = J_{+} - J_{-} = -\int_{-\infty}^{\infty} \frac{\partial \Phi_{1}^{(N)}(J(\lambda), \psi(\lambda), \lambda)}{\partial \psi} d\lambda$$

By virtue of the Cauchy inequality we have, for real ψ ,

$$\left|\frac{\partial \Phi_1^{(N)}}{\partial \psi}\right| \leqslant \frac{2}{z_0} \sup_{|\operatorname{Im} \psi| < 1/2\sigma_0} |\Phi_1^{(N)}|$$

and this yields

$$\Delta I = O\left(\| \Phi_1^{(N)} \| \right) = O\left(\exp\left(-c_1/\epsilon\right) \right)$$

Q.E.D.

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